2018

M.Sc.

4th Semester Examination

APPLIED MATHEMATICS WITH OCEANOLOGY AND COMPUTER PROGRAMMING

PAPER-MTM-404 (OR/OM)

Subject Code-21

Full Marks: 50

Time: 2 Hours

The figures in the right-hand margin indicate full marks.

Candidates are required to give their answers in their own words as far as practicable.

Illustrate the answers wherever necessary.

MTM-404 (OR)

(Non-linear Optimization)

Answer Q. No. 1 and any three from the rest.

1. Answer any five questions:

5×2

(a) Let X° be an open set in Rⁿ, let θ and g be defined on X°. Find the conditions under which a solution (x̄, r̄₀, r̄) of the Fritz-John saddle point problem is a solution of the Fritz-John stationary point problem and conversely.

(Turn Over)

- (b) Define posynomial and polynomial in connection with geometric programming with an example.
- (c) What is the "Theorem of Alternatives" in connection with non-linear programming?
- (d) Define bi-matrix game with an example.
- (e) State Dorn's duality theorem in connection with duality in quadratic programming.
- (f) What is the necessity of constraint qualification related with non-linear programming?
- (g) Write the basic difference(s) between Beale's and Wolfe's method for solving quadratic programming problem.
- (h) Write the advantages of geometric programming.

2. (a) Solve the quadratic programming problem using Wolfe's method

Maximize
$$z = 10x_1 + 25x_2 - 10x_1^2 - x_2^2 - 4x_1x_2$$

subject to $x_1 + 2x_2 \le 10$,

$$x_1 + x_2 \le 9,$$

$$x_1, x_2 \geq 0.$$

- (b) State and prove Weak duality theorem in connection with duality in non-linear programming. 7+3
- 3. (a) Minimize the following using geometric programming $f(x) = 16x_1x_2x_3 + 4x_1x_2^{-1} + 2x_2x_3^{-2} + 8x_1^{-3}x_2$ $x_1, x_2, x_3 > 0.$
 - (b) State and prove Motzkin's theorem of alternative. 6+4
- 4. (a) Define multi-objective non-linear programming problem.
 Define the following in terms of multi-objective non-linear programming problem.
 - (i) Complete optimal solution (ii) Pareto optimal solution

(iii) Local Pareto optimal solution (iv) Weak Pareto optimal solution.

- (b) Give the geometrical interpretations of differentiable convex function and concave function. 2+4+4
- (a) State and prove Fritz-John saddle-point necessary optimality theorem.
 - (b) Use the chance constrained programming to find an equivalent deterministic problem to following stochastic programming problem, when c_j's are random variables

Minimize
$$F(x) = \sum_{j=1}^{n} c_j x_j$$

Subject to $\sum_{j=1}^{n} a_{ij} x_j \le b_i$
 $x_i \ge 0, i, j = 1, 2, ..., n$ 6+4

6. (a) Prove that a pair { y*, z* } constitutes a mixed strategy Nash equilibrium solution to a bimatrix game (A, B) if and only if, there exists a pair {p*, q*} such that {y*, z*, p*, q*} is a solution of the following bilinear programming problem:

Minimize
$$[y'Az + y'Bz + p + q]$$

subject to $Az \ge -pl_m$

$$B'y \ge -ql_n$$

$$y \ge 0, z \ge 0, y'l_m = 1, z'l_n = 1.$$

- (b) Define the following:
 - (i) Kuhn-tucker stationary point problem;
 - (ii) Fritz-john stationary point problem.

6+4

[Internal Assessment: 10 Marks]

MTM-404 (OM)

(Dynamical Oceanology-II)

Answer Q. No. 1 and any four from the rest.

1. Answer any four questions:

4×2

 (a) Calculate the circulation within a small fluid element with area δxδy.

- (b) Calculate the inertial radius for inertial waves for a typical velocity 20 cm/s with a standard Coriolis parameter's value, and Rossby radius of deformation for a deep ocean with height = 3000 m and a shallow ocean with height = 100m.
- (c) Define the vertical velocity in isoberic coordinates and discuss the physical significance for its positive and negative values.
- (d) Derive the depth-integrated continuity equation.
- (e) Write the thermodynamic equation in isobaric coordinate systems. Also explain physical interpretation of each term.
- (f) Derive the ageostrophic continuity equation.
- Derive the Klein-Gordon equation with necessary assumptions.
- 3. For the initial surface elevation

$$\eta_0 = \begin{cases} h \text{ for } y > 0 \\ 0 \text{ for } y < 0 \end{cases}$$

and with the assumption that the motion is independent of x-coordinate, find the stationary surface elevation and the geostrophic velocity distribution.

- 4. (a) Write the depth-averaged 2D shallow water equations and then derive the equation for relative vorticity.
 - (b) For a Couette flow over a plane wall with zero incident, find the relative vorticity. 5+3
- 5. (a) Write the kinematic and dynamic boundary conditions on both the surface (free and bottom) of shallow water theory and hence derive

$$\eta_t = -\frac{\partial}{\partial x} \int_{-H}^{\eta} u dz - \frac{\partial}{\partial y} \int_{-H}^{\eta} v dz \; .$$

- (b) Also derive the hydrostatic equation for this shallow water theory.

 6+2
- 6. (a) Write the x- and y-momentum equations in rectangular coordinate systems and then convert these equations to their isobaric coordinate systems.
 - (b) What are the physical interpretation of each terms of both the equations?

- (a) Write the governing equations for equatorial Kelvin waves and then find the surface elevation and velocity of this wave.
 - (b) Derive the equation for geostrophic relative vorticity and discuss the physical meaning of each term of this equation.

[Internal Assessment: 10 Marks]